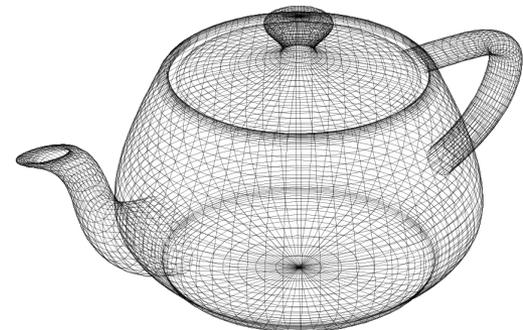
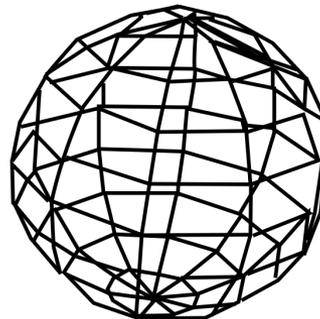
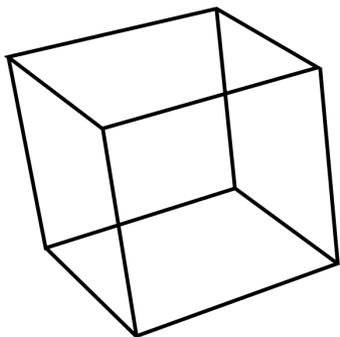


COMPUTER GRAPHICS

Lecture 3: 3D model representation and processing

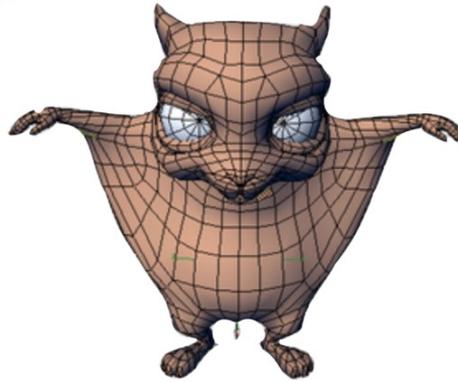
Lecturer: Dr. NGUYEN Hoang Ha



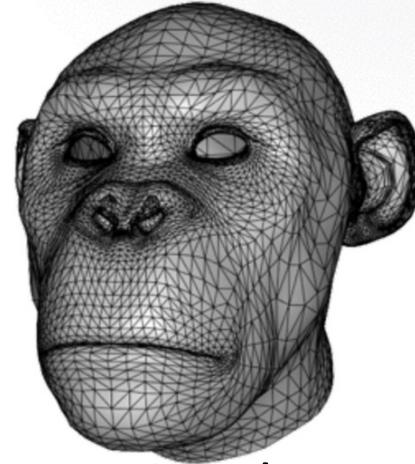
3D



Point cloud



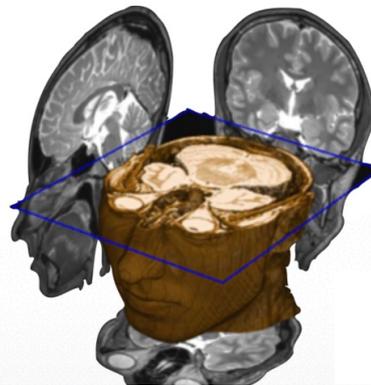
Quad mesh



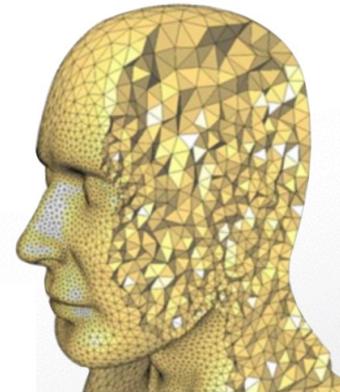
Triangle mesh



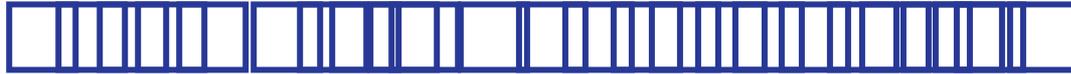
Implicit surface/
particles



Volumetric



Tetrahedrons



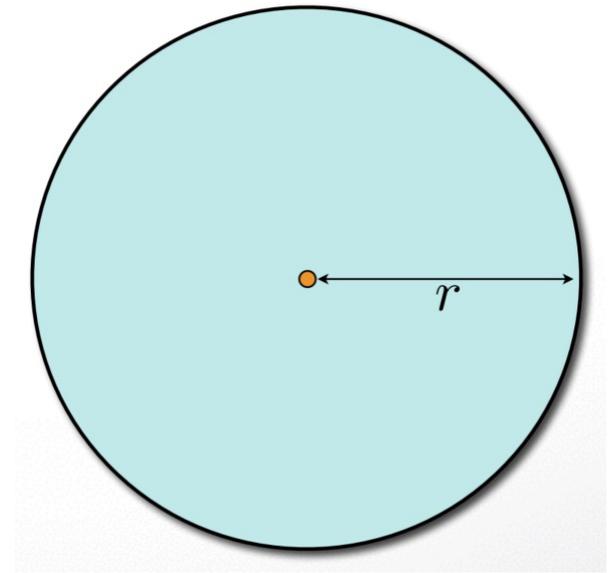
- Surface is the range of a function

$$\mathbf{f} : \Omega \subset \mathbb{R}^2 \rightarrow \mathbb{R}^3, \quad \mathcal{S}_\Omega = \mathbf{f}(\Omega)$$

- 2D example

$$\mathbf{f} : [0, 2\pi] \rightarrow \mathbb{R}^2$$

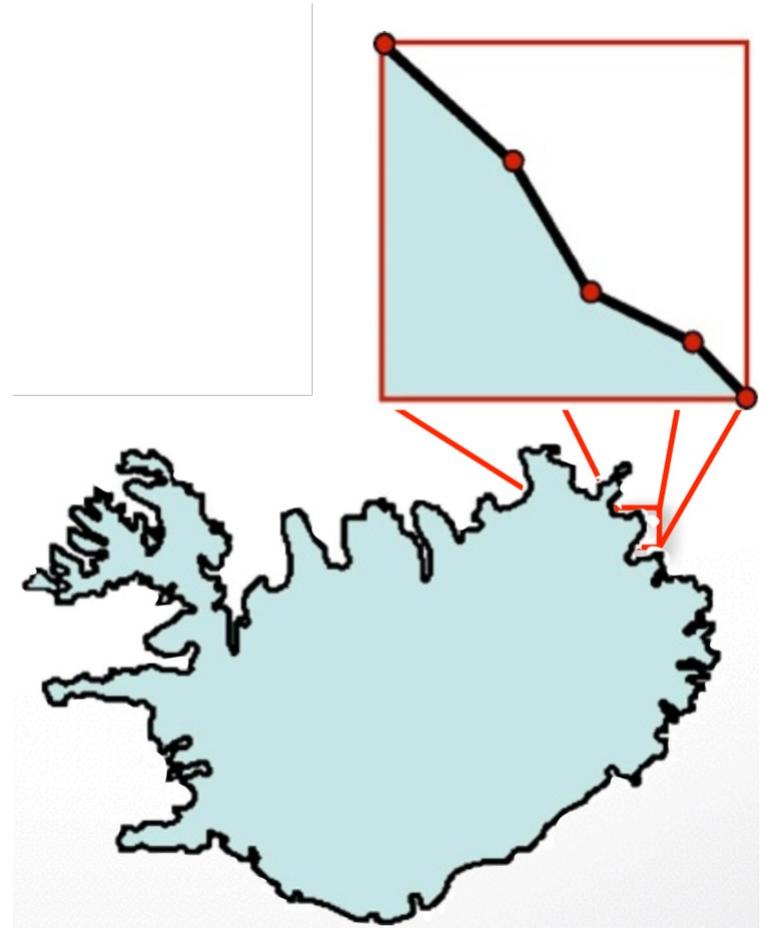
$$\mathbf{f}(t) = \begin{pmatrix} r \cos(t) \\ r \sin(t) \end{pmatrix}$$

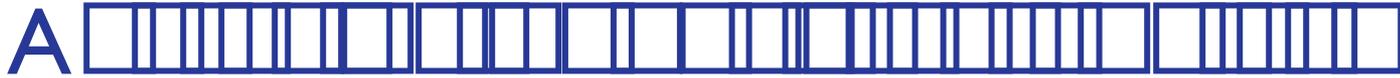




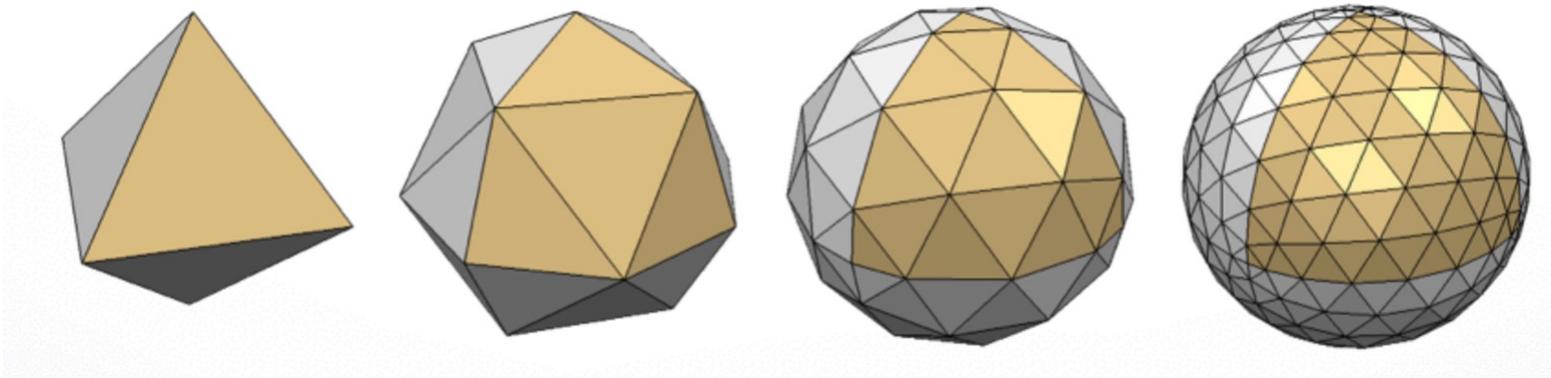
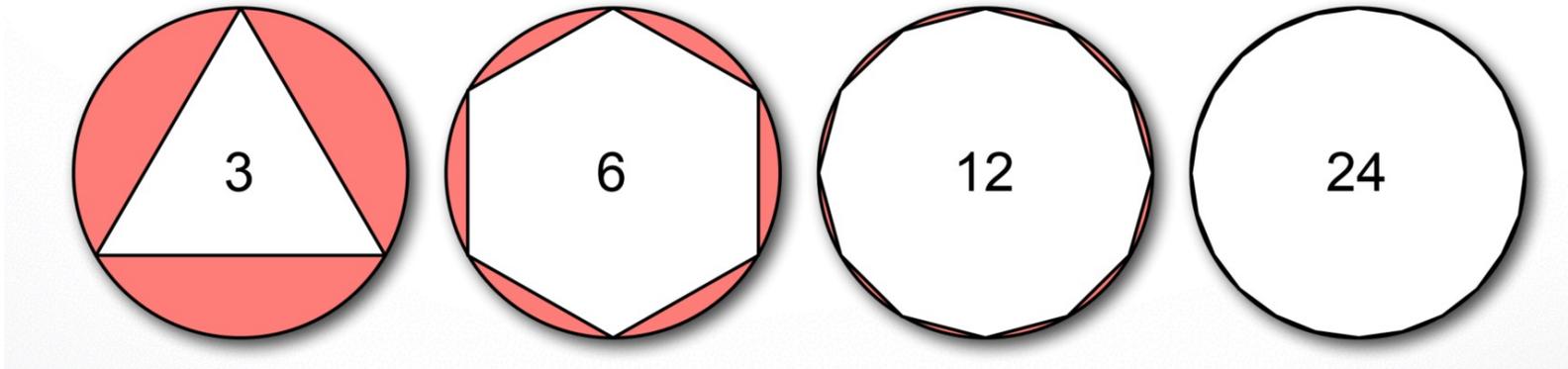
$$\mathbf{f} : [0, 2\pi] \rightarrow \mathbb{R}^2$$

$$\mathbf{f}(t) = \begin{pmatrix} ? \\ ? \end{pmatrix}$$



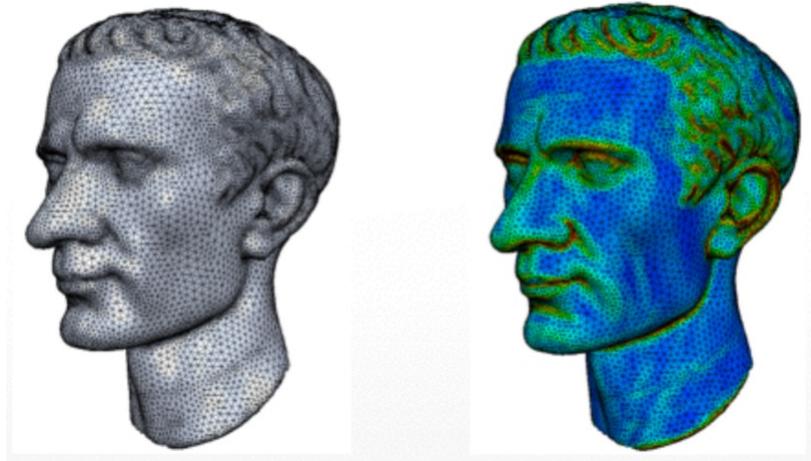


- Error inversely proportional to face number



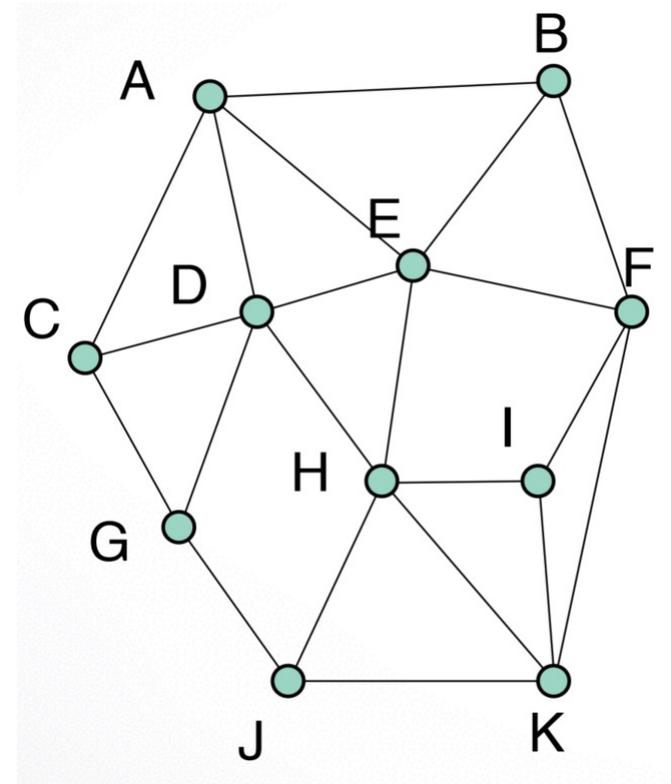


- Error inversely proportional to face number
- Arbitrary topology surface
- Piecewise smooth surface
- Adaptive sampling

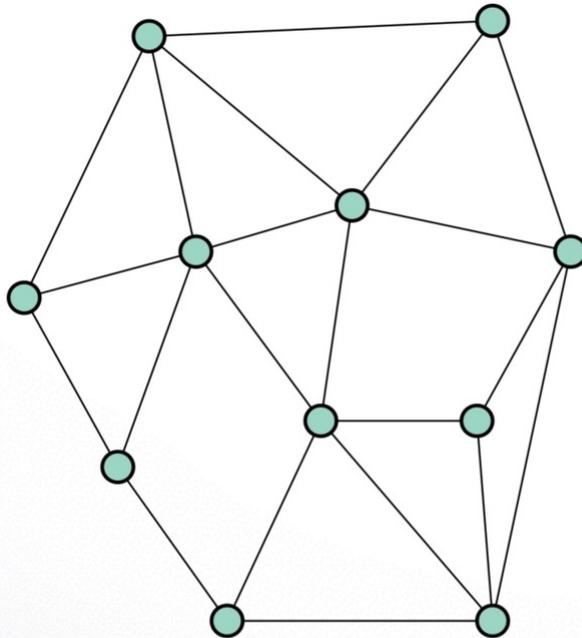




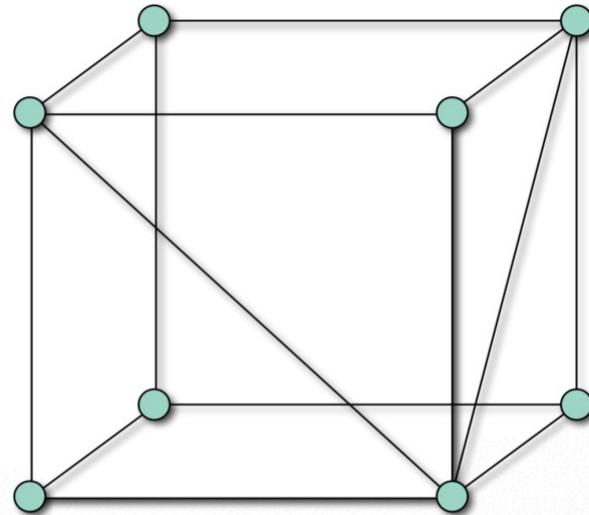
- Graph $\{V, E\}$
- Vertices $V = \{A, B, C... K\}$
- Edges $E = \{(AB), (AE), \dots\}$
- Vertex degree or valance: number of incident edges
 - $D(A) = 4$
 - $D(E) = 5$



- Graph is embedding in \mathbb{R}^d if each vertex is assigned a position in \mathbb{R}^d



Embedding in \mathbb{R}^2



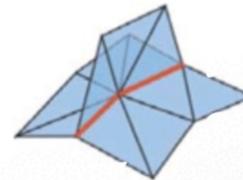
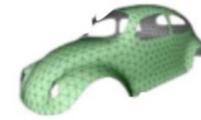
Embedding in \mathbb{R}^3



Embedding in \mathbb{R}^3

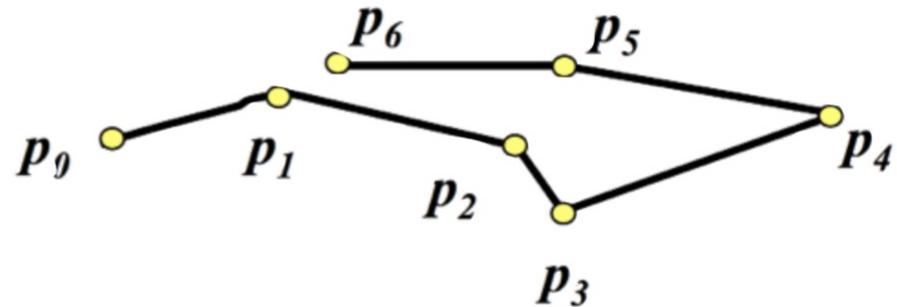


- Mesh: straight-line graph embedded in R^3
- Boundary edge: adjacent to exactly 1 face
- Singular edge: adjacent to more than 2 face
- Regular edge: adjacent to exactly 2 face
- Closed mesh: mesh with no boundary edges





A geometric graph $Q = (V, E)$
 with $V = \{\mathbf{p}_0, \mathbf{p}_1, \dots, \mathbf{p}_{n-1}\}$ in \mathbb{R}^d , $d \geq 2$
 and $E = \{(\mathbf{p}_0, \mathbf{p}_1) \dots (\mathbf{p}_{n-2}, \mathbf{p}_{n-1})\}$
 is called a **polygon**

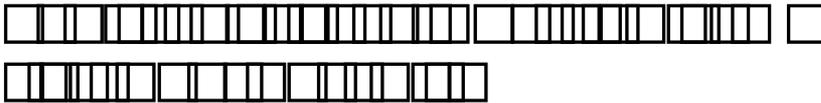


A polygon is called

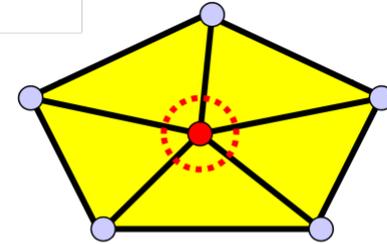
- flat, if all edges are on a plane
- closed, if $\mathbf{p}_0 = \mathbf{p}_{n-1}$



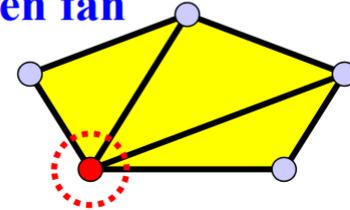
■ A mesh is a manifold if

- 
- 

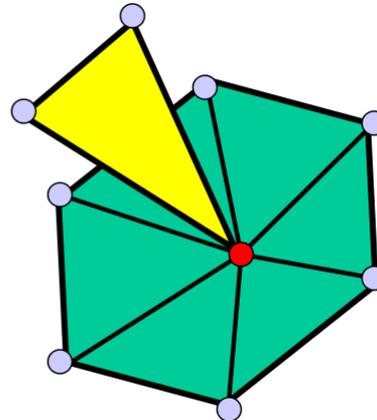
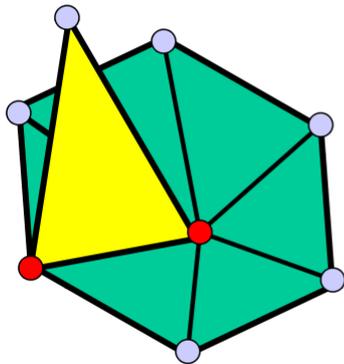
closed fan



open fan

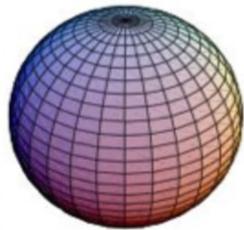


■ Non-manifold meshes

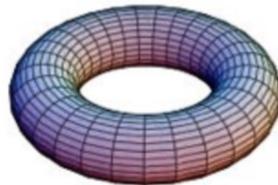




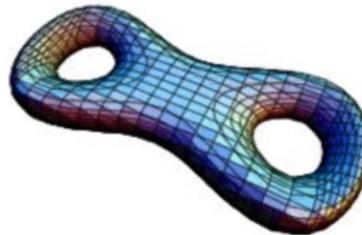
- **Genus:** Maximal number of closed simple cutting curves that do not disconnect the graph into multiple components.
- Or half the maximal number of closed paths that do not disconnect the mesh
- Informally, the number of **holes** or **handles**



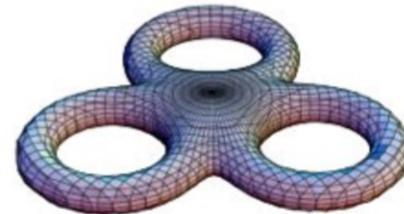
Genus 0



Genus 1



Genus 2



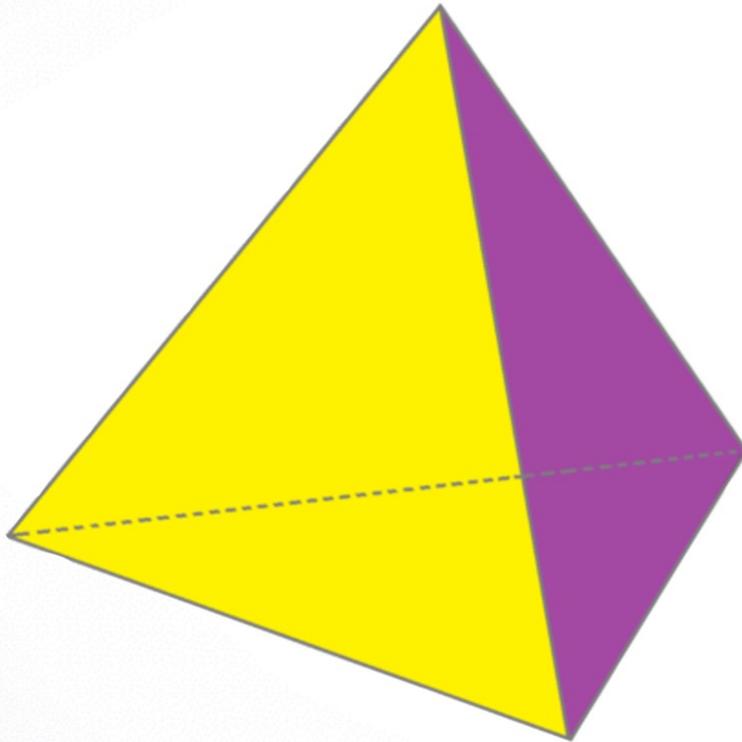
Genus 3



- For a closed polygonal mesh of **genus** g , the relation of the number V of vertices, E of edges, and F of faces is given by **Euler's formula**:

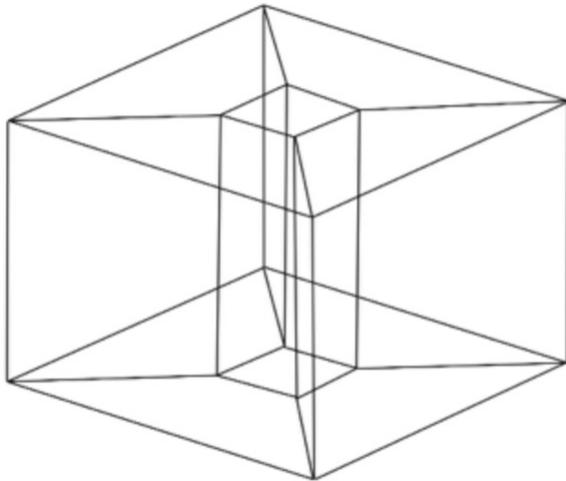
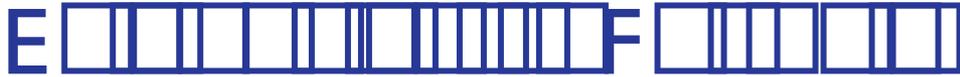
$$V - E + F = 2(1 - g)$$

- The term $2(1 - g)$ is called the **Euler characteristic** χ



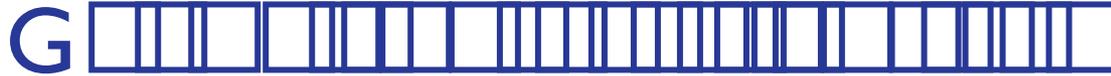
$$V - E + F = 2(1 - g)$$

$$4 - 6 + 4 = 2(1 - 0)$$



$$V - E + F = 2(1 - g)$$

$$16 - 32 + 16 = 2(1 - 1)$$



- Surface reconstruction
- Surface smoothing (noise removal)
- Surface simplification
- Remeshing for improving mesh quality



- Principal curvatures K_1 and K_2 : the two principal curvatures at a given point of a surface are the maximum and minimum values of the curvature as expressed by the eigenvalues of the shape operator at that point.
- Gaussian curvature: $K = K_1 K_2$
- Mean curvature:
- Maximum curvature: $\max(K_1, K_2)$
- Minimum curvature: $\min(K_1, K_2)$

